	Hits	Search Text
1	3071	automat\$4 and (arm\$2 with gripper)
2	315	automat\$4 with (arm\$2 with gripper)
3	203	(automat\$4 with (arm\$2 with gripper)) and rotat\$5
4	976	automat\$4 with (arm\$2 with grip\$4)
5	233	(automat\$4 with (arm\$2 with grip\$4)) and (grip\$4 near4 rotat\$5)
6	216	(automat\$4 and (arm\$2 with gripper) and telescop\$4) and rotat\$4
7	4469	(422/63-67,300-304).CCLS.
8	1305	((422/63-67,300-304).CCLS.) and arm\$4
9	289	(((422/63-67,300-304).CCLS.) and arm\$4) and grip\$5
10	247	((((422/63-67,300-304) CCLS.) and arm\$4) and grip\$5) and rotat\$5
11	9	((((((422/63-67,300-304).CCLS.) and arm\$4) and grip\$5) and rotat\$5) and telescop\$4
12	12	(automat\$4 or robot\$2) with (arm\$2 with gripper) with telescop\$3
13	120	(automat\$4 or robot\$2) with ((shaft\$2 or rail\$2) near3 telescop\$3)
14	13	((automat\$4 or robot\$2) with ((shaft\$2 or rail\$2) near3 telescop\$3)) with arm\$2
15	45	((automat\$4 or robot\$2) with ((shaft\$2 or rail\$2) near3 telescop\$3)) and arm\$2

16 1498 (automat\$4 or robot\$2) with (arm\$2 with grip 17 93 ((automat\$4 or robot\$2) with (arm\$2 with grip 18 4726 (901/1-9,14-29).CCLS. 19 543 ((901/1-9,14-29).CCLS.) and gripper\$3 20 143 (((901/1-9,14-29).CCLS.) and gripper\$3) and 21 2023 two near2 grippers 22 49 (two near2 grippers) near4 drive\$2 23 104 (robot\$4 or automat\$4) and (telescop\$3 near3 adjust\$5) 24 61 ((robot\$4 or automat\$4) and (telescop\$3 near adjust\$5)) and arm\$2 25 117 (robot\$4 or automat\$4) and (telescop\$3 near3 adjust\$5) ((robot\$4 or automat\$4) and (telescop\$3 near3 adjust\$5)) and arm\$2	oper)) and (drive
17 93 near2 belt\$2) 18 4726 (901/1-9,14-29).CCLS. 19 543 ((901/1-9,14-29).CCLS.) and gripper\$3 20 143 (((901/1-9,14-29).CCLS.) and gripper\$3) and 21 2023 two near2 grippers 22 49 (two near2 grippers) near4 drive\$2 23 104 (robot\$4 or automat\$4) and (telescop\$3 near3 adjust\$5) 24 61 ((robot\$4 or automat\$4) and (telescop\$3 near adjust\$5)) and arm\$2 25 117 (robot\$4 or automat\$4) and (telescop\$3 near3	
19 543 ((901/1-9,14-29).CCLS.) and gripper\$3 20 143 (((901/1-9,14-29).CCLS.) and gripper\$3) and 21 2023 two near2 grippers 22 49 (two near2 grippers) near4 drive\$2 23 104 (robot\$4 or automat\$4) and (telescop\$3 near3 adjust\$5) 24 61 ((robot\$4 or automat\$4) and (telescop\$3 near adjust\$5)) and arm\$2 25 117 (robot\$4 or automat\$4) and (telescop\$3 near3	belt\$2
20 143 (((901/1-9,14-29).CCLS.) and gripper\$3) and 21 2023 two near2 grippers 22 49 (two near2 grippers) near4 drive\$2 23 104 (robot\$4 or automat\$4) and (telescop\$3 near3 adjust\$5) 24 61 ((robot\$4 or automat\$4) and (telescop\$3 near adjust\$5)) and arm\$2 25 117 (robot\$4 or automat\$4) and (telescop\$3 near adjust\$5)	belt\$2
two near2 grippers (two near2 grippers) near4 drive\$2 (robot\$4 or automat\$4) and (telescop\$3 near3 adjust\$5) ((robot\$4 or automat\$4) and (telescop\$3 near adjust\$5)) and arm\$2 (robot\$4 or automat\$4) and (telescop\$3 near adjust\$5)) and arm\$2	belt\$2
22 49 (two near2 grippers) near4 drive\$2 23 104 (robot\$4 or automat\$4) and (telescop\$3 near3 adjust\$5) 24 61 ((robot\$4 or automat\$4) and (telescop\$3 near adjust\$5)) and arm\$2 25 117 (robot\$4 or automat\$4) and (telescop\$3 near adjust\$5)	
23 104 (robot\$4 or automat\$4) and (telescop\$3 near3 adjust\$5) 24 61 ((robot\$4 or automat\$4) and (telescop\$3 near adjust\$5)) and arm\$2 25 117 (robot\$4 or automat\$4) and (telescop\$3 near adjust\$5) and arm\$2	
24 61 ((robot\$4 or automat\$4) and (telescop\$3 near adjust\$5)) and arm\$2 25 117 (robot\$4 or automat\$4) and (telescop\$3 near3	
adjust\$5)) and arm\$2 25 117 (robot\$4 or automat\$4) and (telescop\$3 near3	height near3
	3 height near3
(automat\$4 or robot\$2) with ((shaft\$2 or rail\$	height) and arm\$2
height) near3 telescop\$3)	2 or arm\$2 or
27 95 ((automat\$4 or robot\$2) with ((shaft\$2 or rail height) near3 telescop\$3)) and height	\$2 or arm\$2 or
28 2 ("5215377").PN.	
29 9 grippers near4 independent near3 drive\$3	
30 1098 grippers near4 drive\$3	

	Hits	Search Text
31	75	(grippers near4 drive\$3) with arm\$2
32	241	((two or pair) near2 grippers) with arm
33	18	(((two or pair) near2 grippers) with arm) with (belt or drive\$2)
34	2	("6652015").PN.
35	289	((plural\$4 or two or couple or pair) near2 grippers) with arm
36	6	(("6,080,363") or ("5948159") or ("5,417,123")) PN
37	15	"2196428"
38	3	"GB 2196428"
39	2	("4738824").PN.
40	2	("5,895,628") PN